

## Gaussian Elimination as a Matrix Factorization

Each of the elementary row operations from Gaussian Elimination (GE) has associated with it a nonsingular matrix with the property that multiplying (on the left) by that associated matrix gives the same result as applying the row operation.

1. **Row operation 1 (R1):** Multiply row  $i$  by a scalar  $\alpha \neq 0$ .

**Associated matrix:** Let  $D$  be the identity matrix except for the  $(i, i)$  element, which is  $\alpha$ . Then the matrix  $DA$  is the result of R1 applied to  $A$ .

2. **Row operation 2 (R2):** Interchange row  $i$  and row  $j$ .

**Associated matrix:** Let  $P$  be the identity matrix with rows  $i$  and  $j$  interchanged. Then the matrix  $PA$  is the result of R2 applied to  $A$ .

3. **Row operation 3 (R3):** Multiply row  $j$  by a scalar  $m$  and add it to row  $i$ .

**Associated matrix:** Let  $M$  be the identity but with  $m$  replacing the 0 in the  $(i, j)$  position. Then  $M = I + me_i e_j^t$ , and the matrix  $MA$  is the result of R3 applied to  $A$ . Taking  $m = m_{ij} = -a_{ij}/a_{jj}$  puts a zero in the  $(i, j)$  position of  $MA$ .

**Example** Let  $A = \begin{bmatrix} a_1^t \\ a_2^t \\ a_3^t \end{bmatrix} \in \mathbb{R}^{3 \times n}$ , that is, the  $i^{\text{th}}$  row of  $A$  is  $a_i^t$ .

$$\text{Let } D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \alpha & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \quad \text{and} \quad M = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ m & 0 & 1 \end{bmatrix}.$$

$$\text{Then } DA = \begin{bmatrix} a_1^t \\ \alpha a_2^t \\ a_3^t \end{bmatrix}, \quad PA = \begin{bmatrix} a_1^t \\ a_3^t \\ a_2^t \end{bmatrix}, \quad \text{and} \quad MA = \begin{bmatrix} a_1^t \\ a_2^t \\ a_3^t + ma_1^t \end{bmatrix}.$$

A nonsingular matrix can *always* be triangularized by GE using only operations R2 and R3, and *almost always* using only R3:

If  $a_{11} \neq 0$ , then R3 can be used  $n - 1$  times to zero out all elements below the  $(1, 1)$  position. The new matrix, call it  $A^{(1)}$ , is related to  $A$  by

$$A^{(1)} = M_{n,1} M_{n-1,1} \cdots M_{2,1} A \equiv M_1 A.$$

$M_1$  is called a *Gauss Transform*; take some time to digest this:

$$M_1 = M_{n,1} \cdots M_{2,1} = (I + m_{n,1} e_n e_1^t) \cdots (I + m_{2,1} e_2 e_1^t) = I + m_1 e_1^t,$$

where  $m = (0, m_{2,1}, m_{3,1}, \dots, m_{n,1})^t$ . If  $a_{kk}^{(k-1)} \neq 0$ ,  $k = 1, 2, \dots, n - 1$ , then we can triangularize  $A$ :

$$A^{(k)} = M_{n,k} M_{n-1,k} \cdots M_{k+1,k} A^{(k-1)} \equiv M_k \cdots M_2 M_1 A,$$

and  $A^{(n-1)} = M_{n-1} \cdots M_2 M_1 A \equiv U$  is upper triangular. Set  $L = (M_k \cdots M_2 M_1)^{-1}$ . As a product of lower triangular matrices  $((I + m_k e_k^t)(I - m_k e_k^t) = I!)$ ,  $L$  is lower triangular, and we have the factorization  $A = LU$ .