

Name: \_\_\_\_\_

(15) 1. Given  $A = LU$  with  $L = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \end{bmatrix}$  and  $U = \begin{bmatrix} -1 & 0 & 2 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$ .

(a) Solve  $Ax = b$ , where  $b = (-1, 3, 9)^t$ .

(b) What multiplier was used to introduce a zero at the  $(3, 1)$  position of  $A$ ?

(18) 2. On Norms

(a) Define the norm on  $\mathbb{R}^{m \times n}$  induced by  $\|\cdot\|_1$  on  $\mathbb{R}^n$  and  $\|\cdot\|_\infty$  on  $\mathbb{R}^m$ .

(b) Is  $f(A) = \max_{1 \leq i, j \leq n} |a_{ij}|$  a norm on  $\mathbb{R}^{n \times n}$ ? Why or why not?

(c) Let  $A = \begin{bmatrix} 1 & 2 & -3 \\ 2 & -2 & 2 \end{bmatrix}$ . Compute  $\|A\|_1$ .

- (18) 3. On Conditioning and Stability
- (a) Define what it means for a method to be backward stable.
  
  - (b) Define what it means for a problem to be well conditioned.
  
  - (c) Using the ideas of conditioning and stability, describe the conditions under which we expect a computed solution to be a good approximation to the true solution.
- (16) 4. Gaussian Elimination with partial pivoting (GEPP).
- (a) Describe why pivoting is needed in the floating point implementation of Gaussian Elimination.
  
  - (b) Describe the matrix factorization that is given by GE with partial pivoting. Carefully describe that matrices that result.
  
  - (c) What are the steps needed to solve  $Ax = b$  if one already has GEPP completed?

(15) 5. Compute the  $A = LU$  factorization of  $A = \begin{bmatrix} -1 & 1 & 2 \\ 2 & -4 & -3 \\ -3 & 3 & 9 \end{bmatrix}$ .

(18) 6. Let  $\hat{x}$  be an approximate solution to  $Ax = b$ . Let  $r = b - A\hat{x}$  be its residual, and let  $e = x - \hat{x}$  be the error. Suppose the matrix and vector norms satisfy  $\|Ax\| \leq \|A\|\|x\|$ .

(a) Show that  $\|e\| \leq \|A^{-1}\|\|r\|$ .

(b) Now show that  $\frac{\|e\|}{\|x\|} \leq \kappa(A) \frac{\|r\|}{\|b\|}$ .

(c) Does a small residual mean  $\hat{x}$  is close to  $x$ ? Explain.